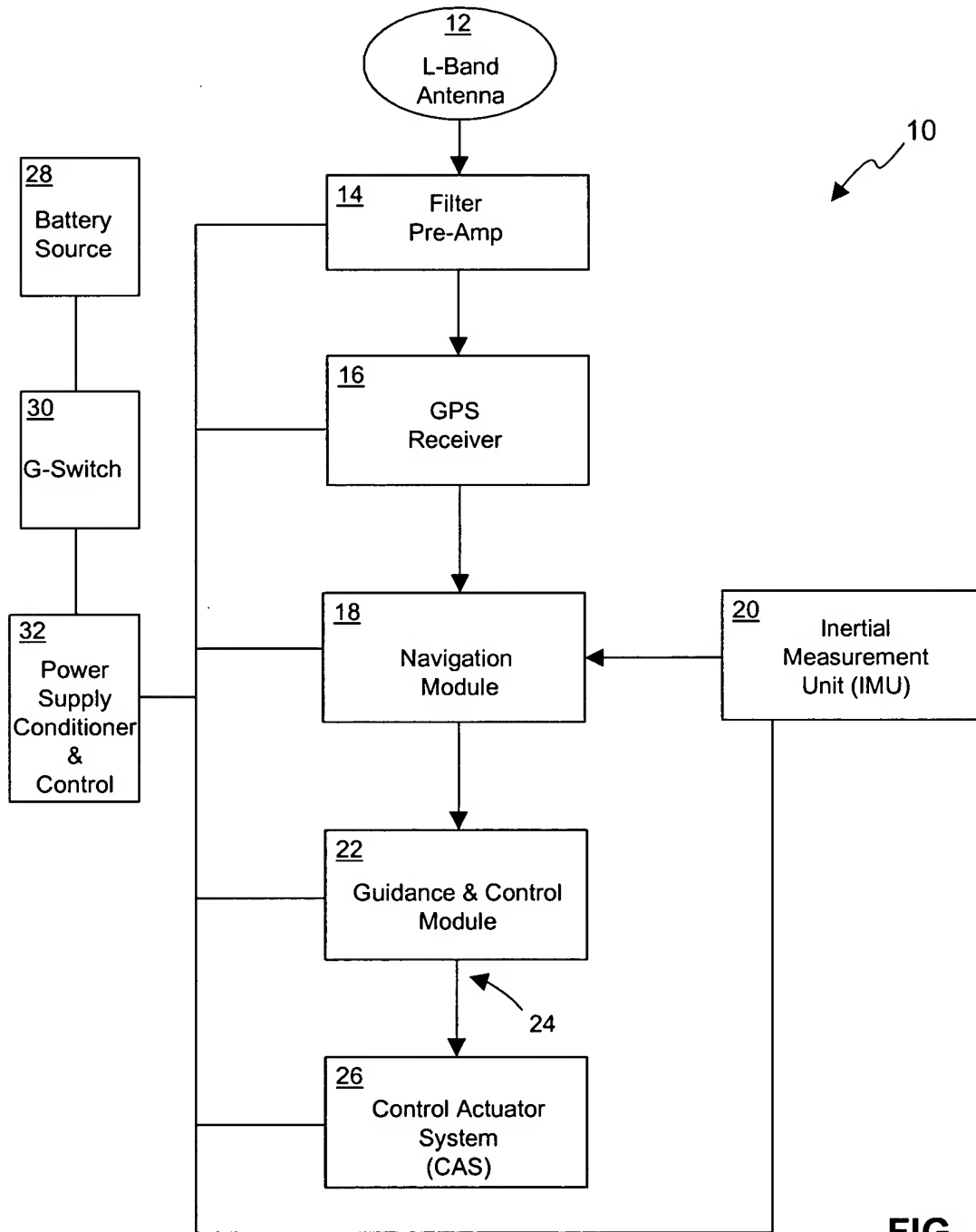


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**FIG. 1**

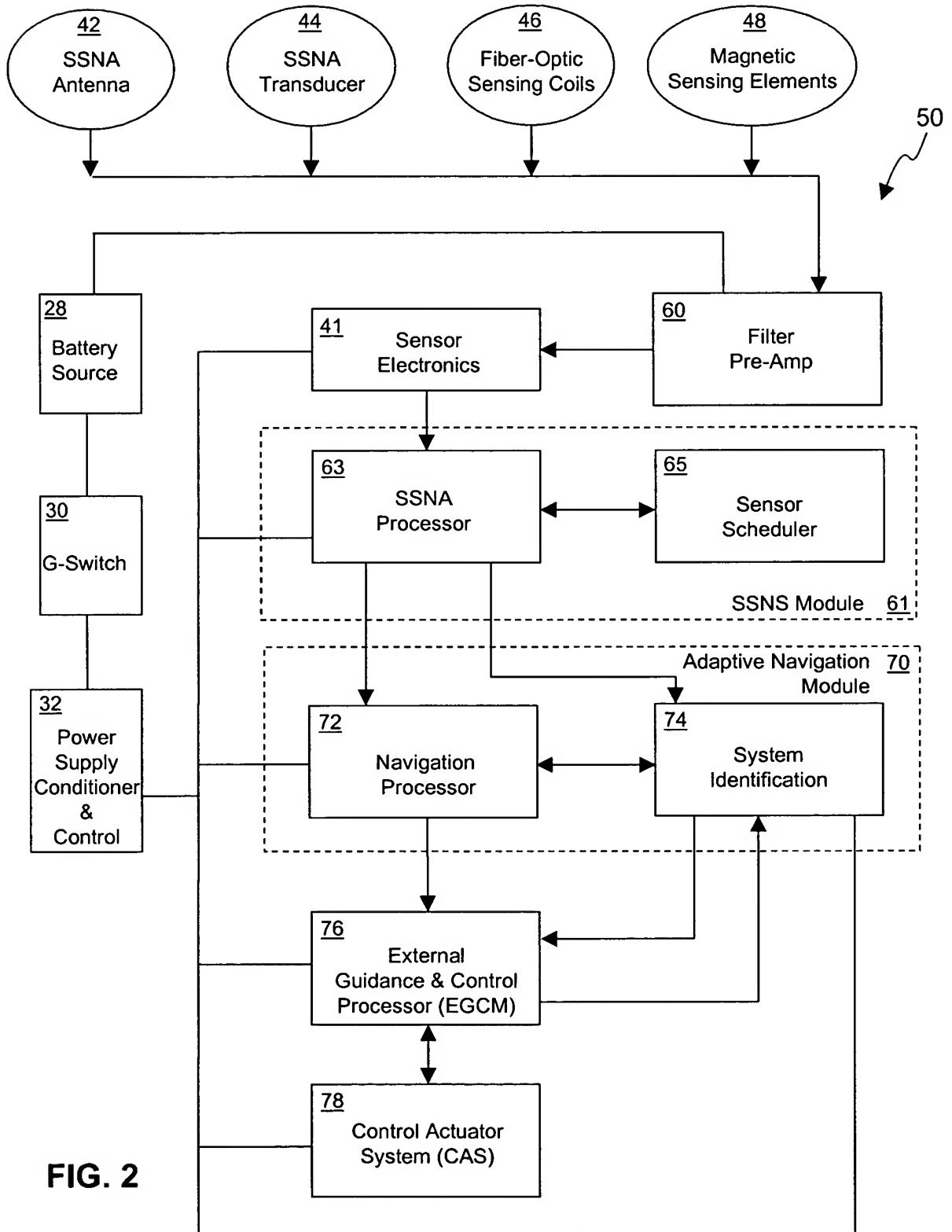
**(Prior Art)**

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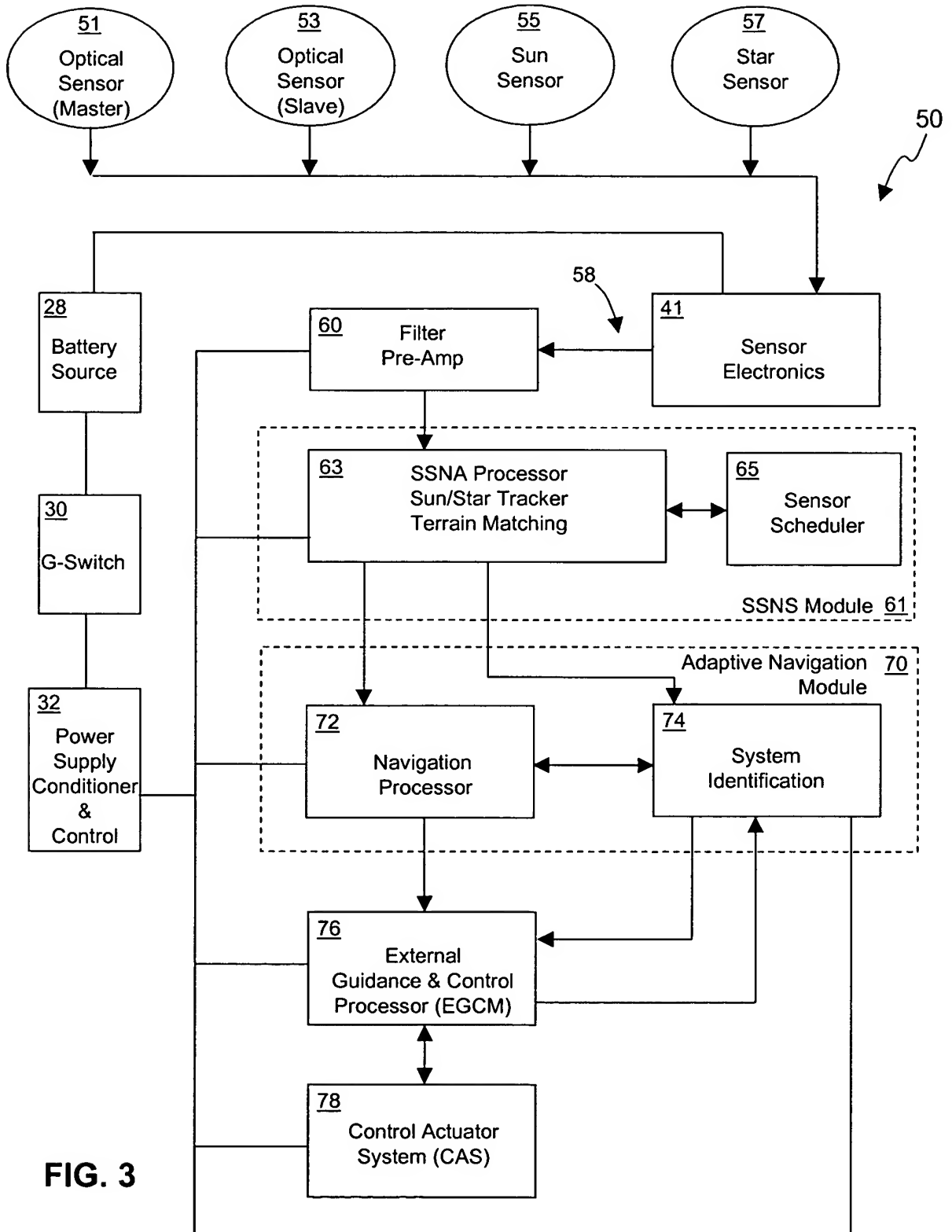


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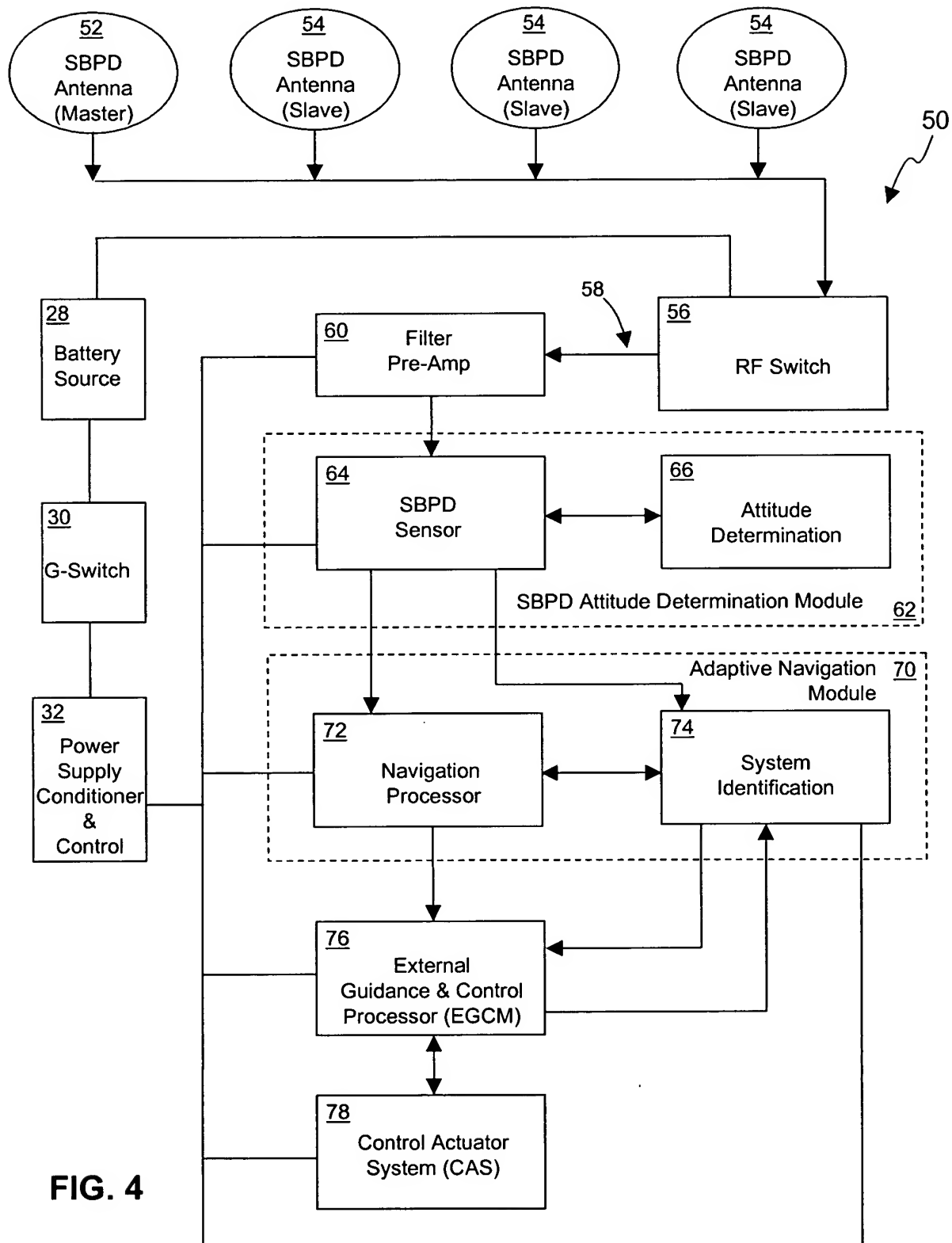
**FIG. 3**

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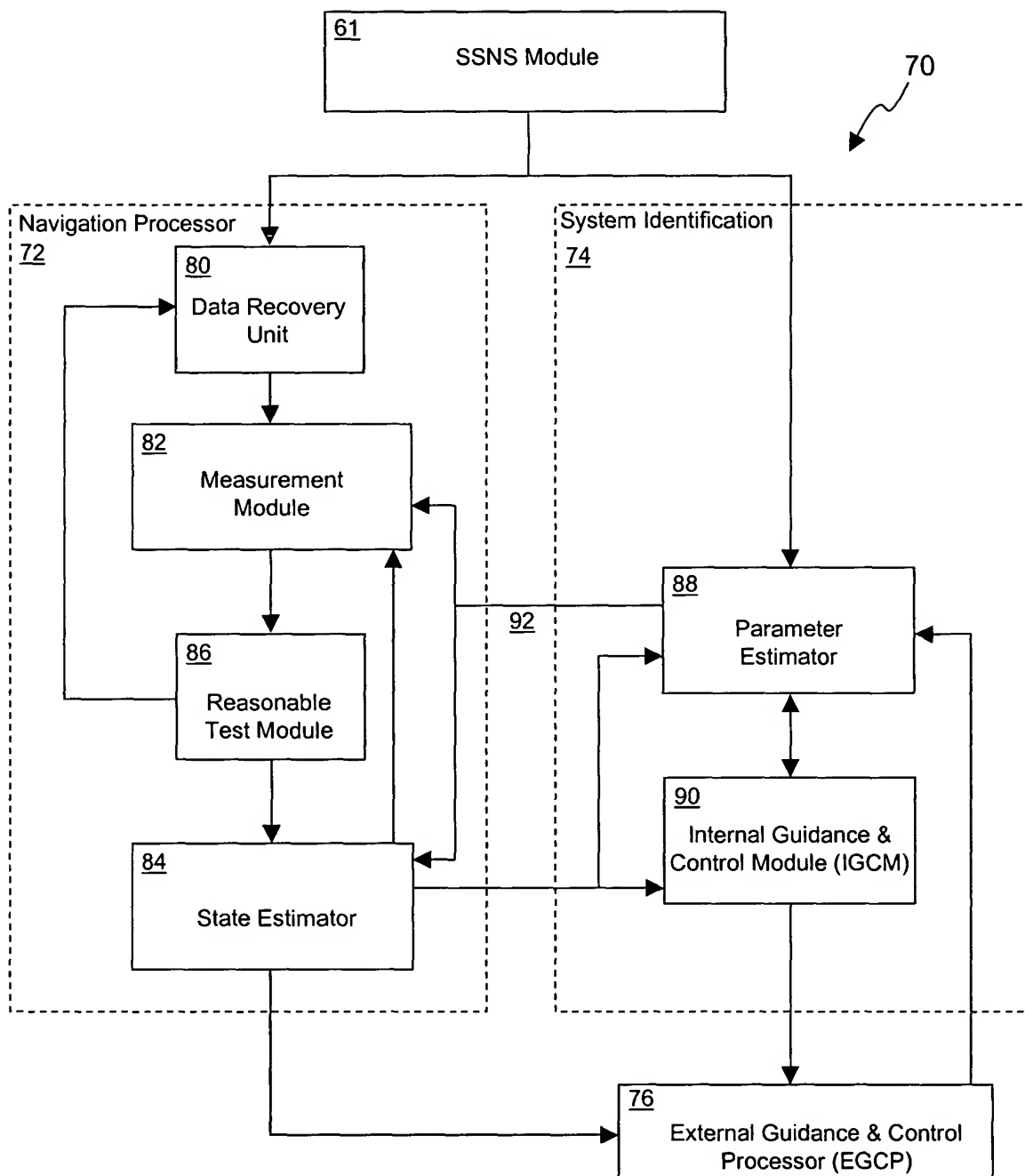


FIG. 5

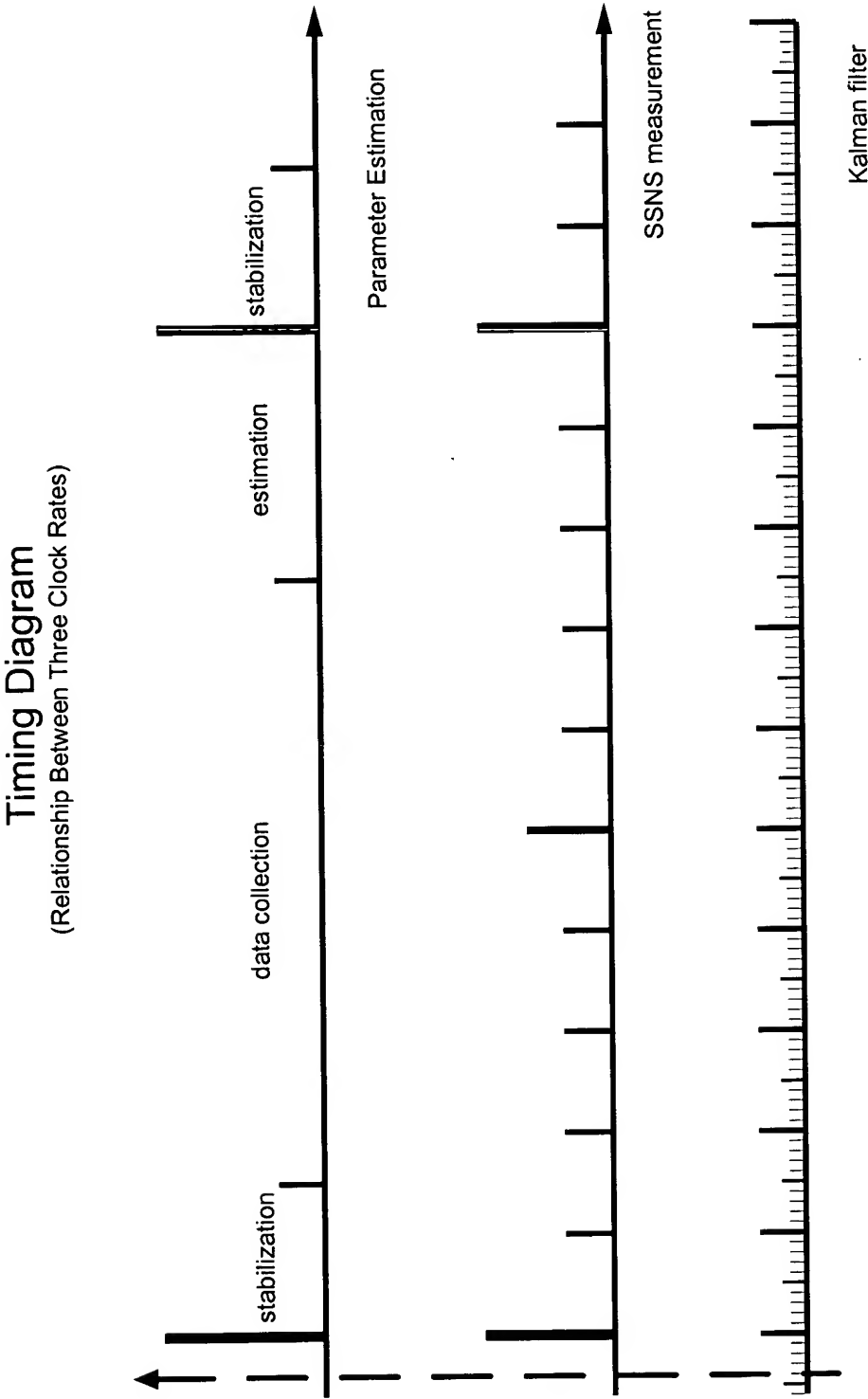


FIG. 6

Projectile Velocity, Deficit Velocity, and Correction Velocity  
(Calculated with respect to an Inertial Frame of Reference)

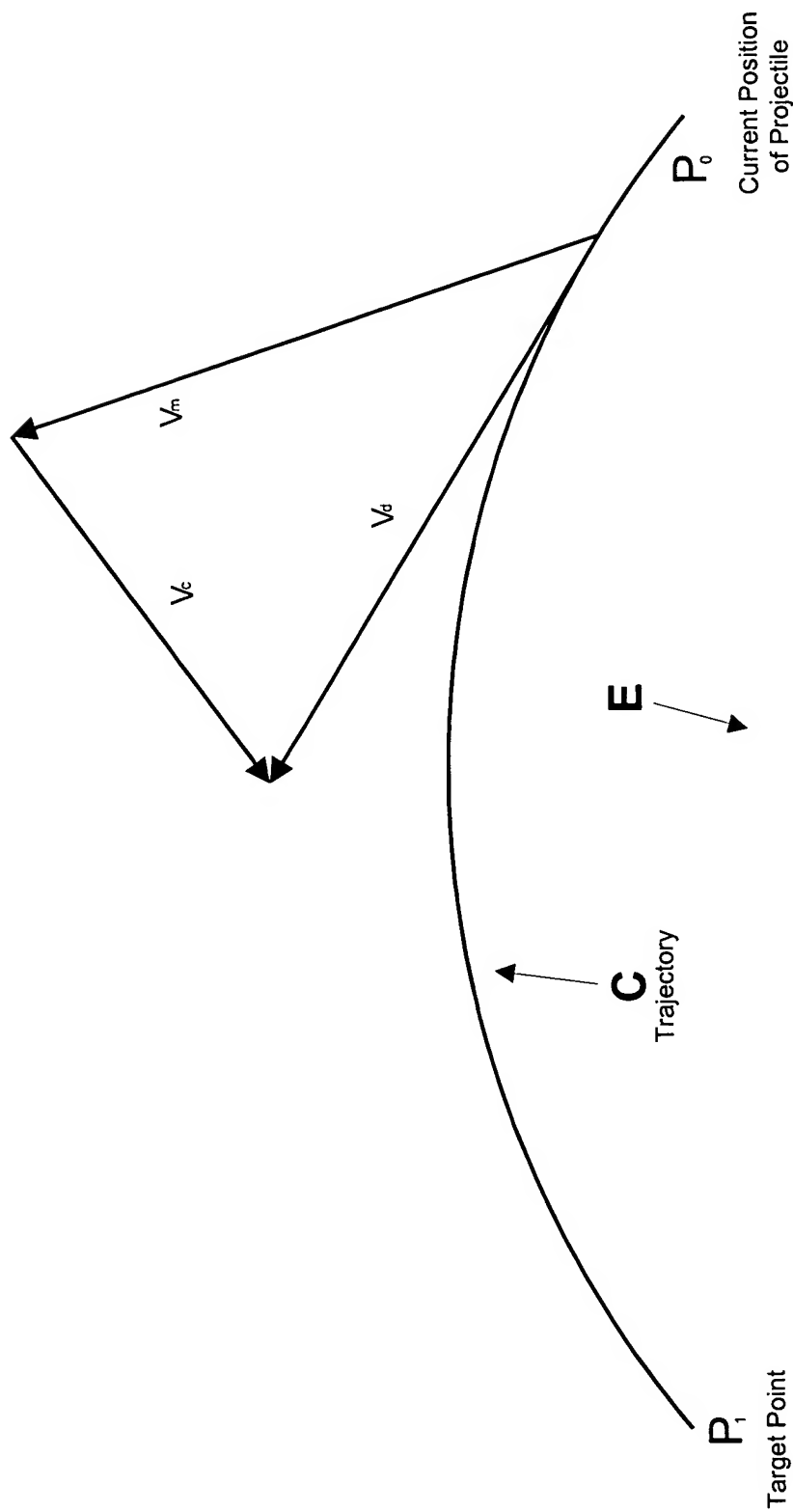


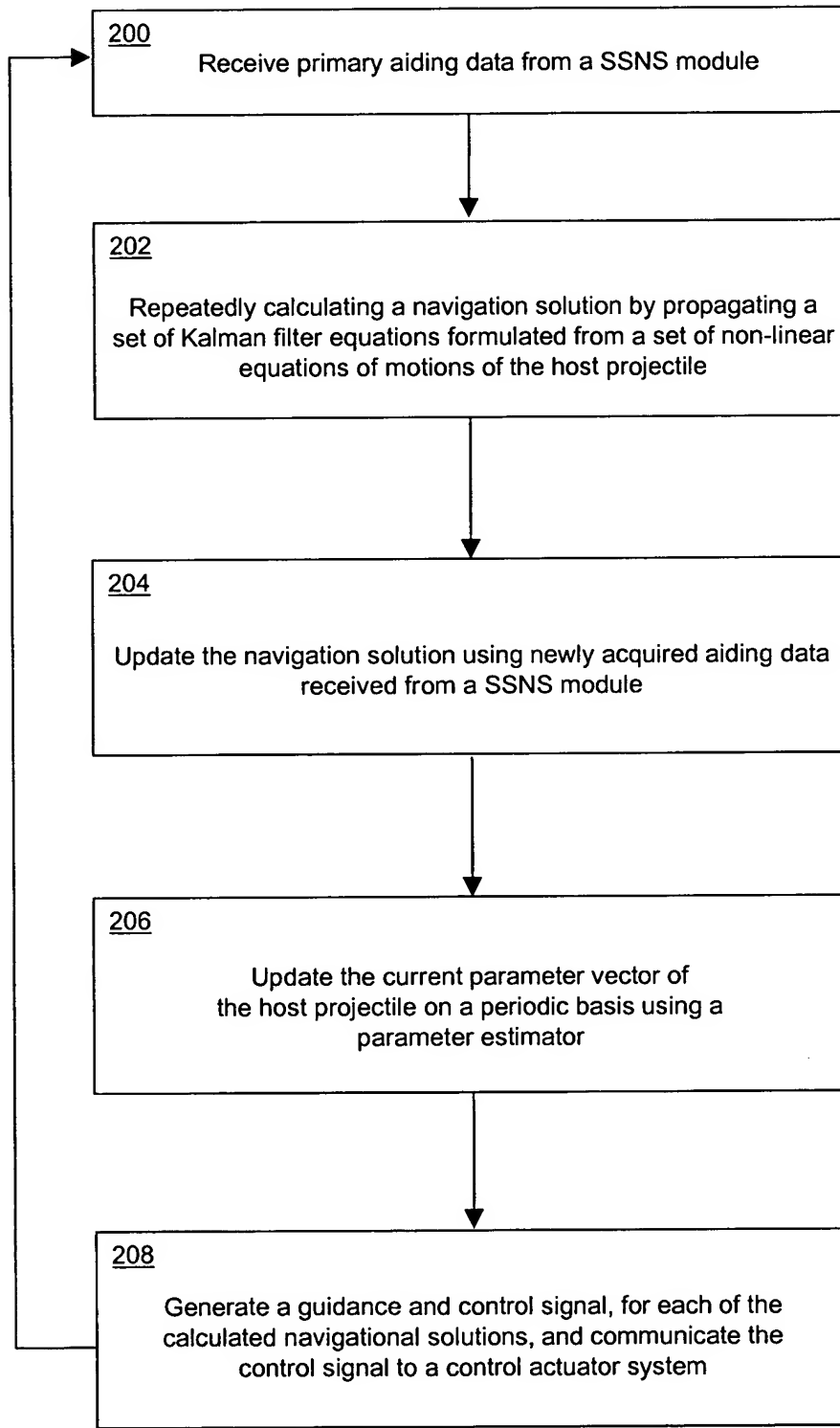
FIG. 7

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**FIG. 8**

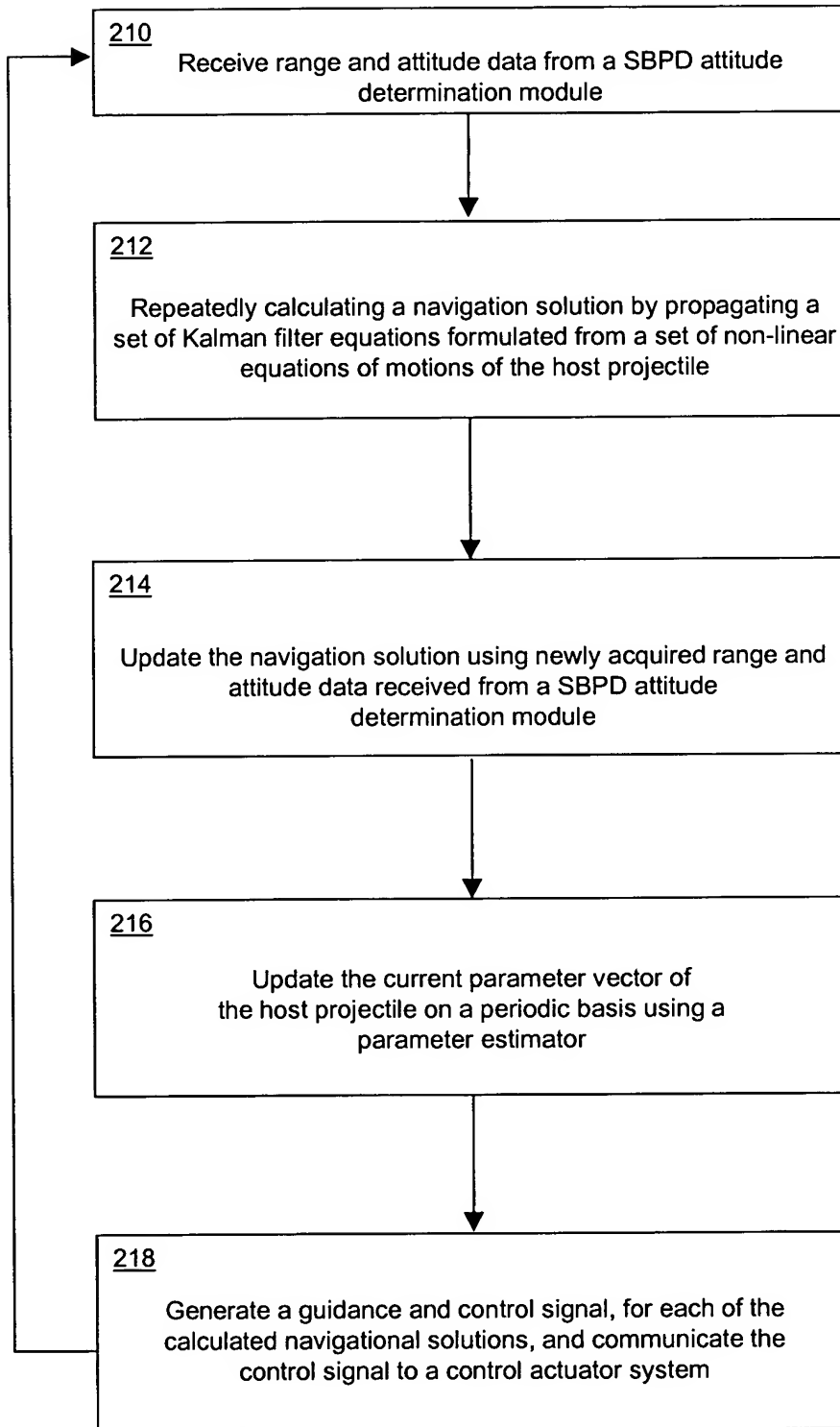


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**FIG. 9**

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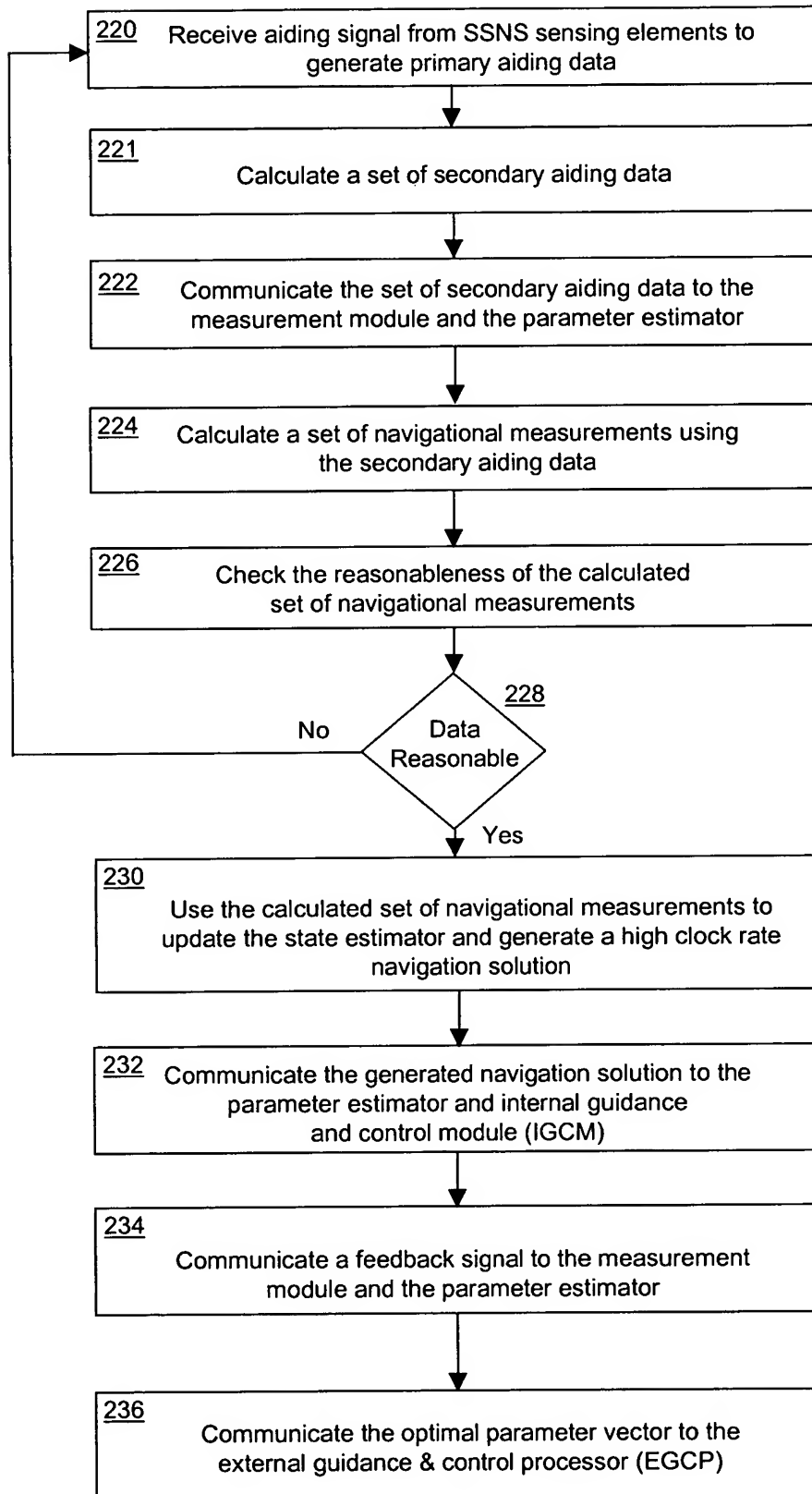


FIG. 10

MULTI-SENSOR GUIDANCE SYSTEM FOR EXTREME FORCE  
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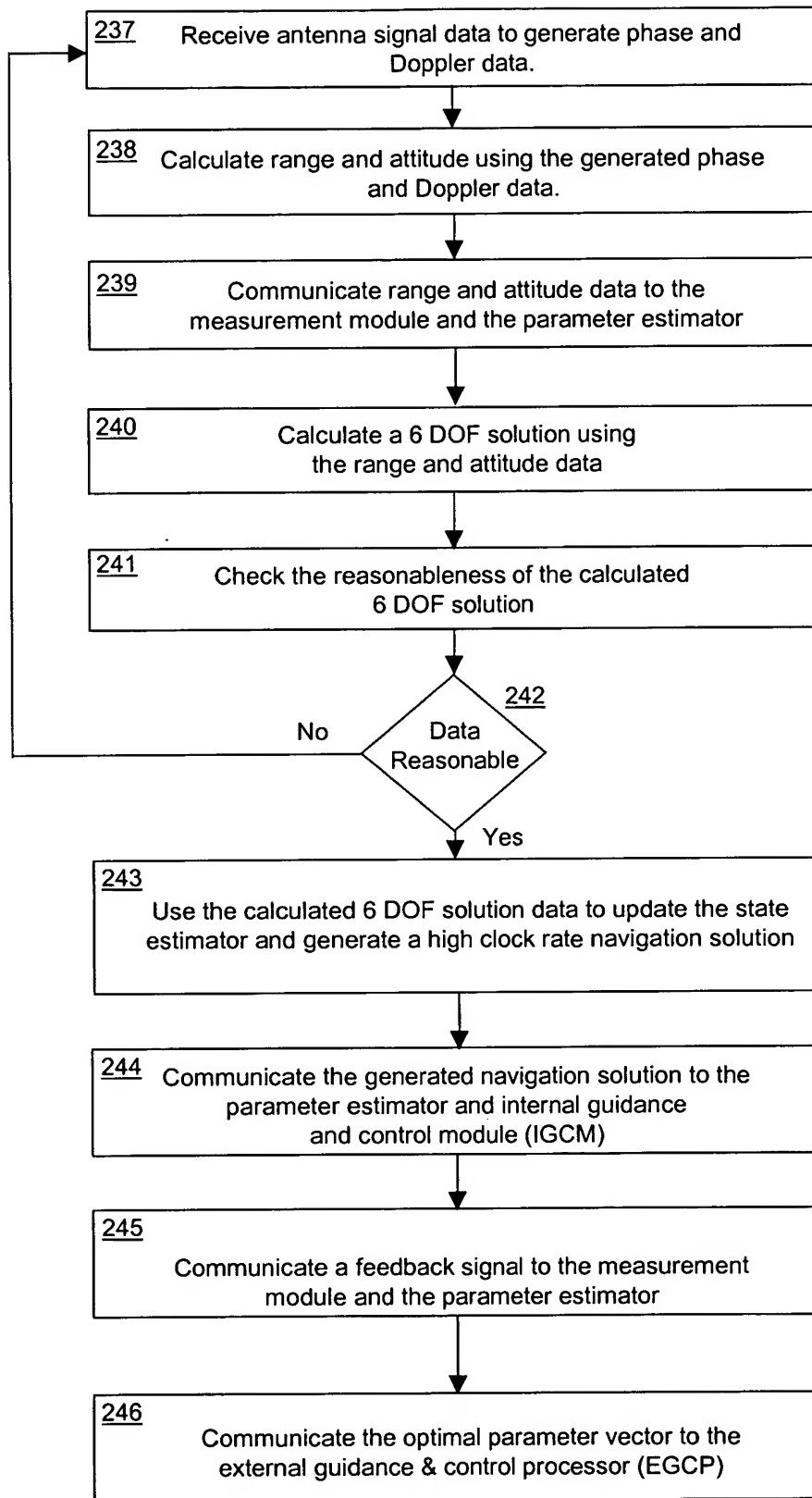


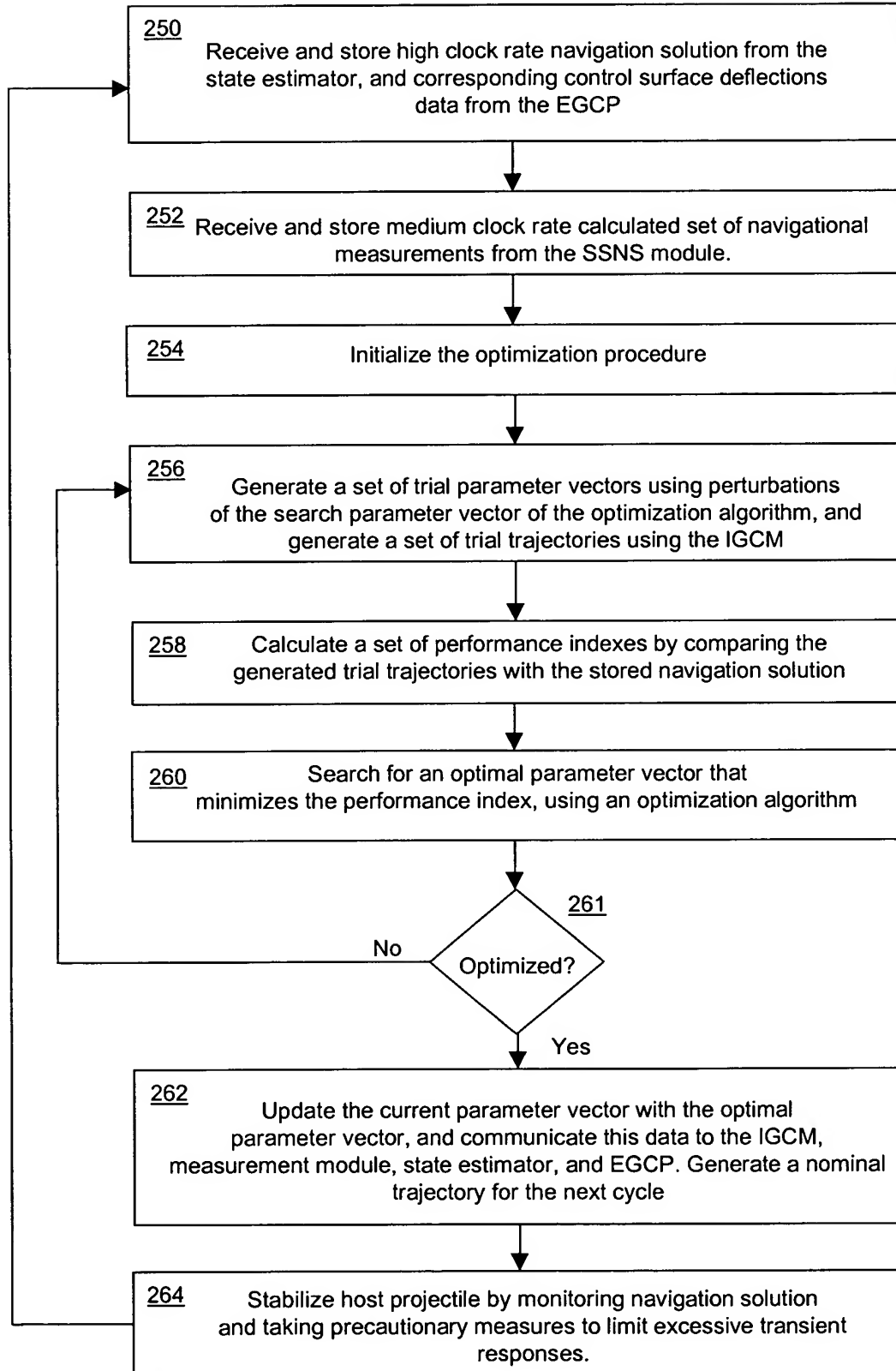
FIG. 11

**MULTI-SENSOR GUIDANCE SYSTEM FOR EXTREME FORCE  
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**FIG. 12**